

No.	Title	Code	Organizer Name	Institution	E-mail Address
1	Intelligent Safe and Secure Control of Unmanned Aerial Systems	KxgCME	Ziquan Yu	Nanjing University of Aeronautics and Astronautics	yuziquan@nuaa.edu.cn
			Youmin Zhang	Concordia University	youmin.zhang@concordia.ca
			Bin Jiang	Nanjing University of Aeronautics and Astronautics	binjiang@nuaa.edu.cn
2	Learning-Based Intelligent Control, Decision-Making, and Perception for Unmanned Systems	oHnkzR	Yueying Wang	Shanghai University	yueyingwang@shu.edu.cn
			Zhi Chen	Shanghai University	ychen183@shu.edu.cn
			Jian Fu	Nanjing University of Science and Technology	hcyan@ecust.edu.cn
			Xiaolan Xie	Guilin University of Technology	xxl@glut.edu.cn
3	Advanced control method for intelligent unmanned system	m43dpq	Kun Yan	Xi'an Technological University	yankun@xatu.edu.cn
			Haidong Shen	Nanjing University of Aeronautics and Astronautics	shenhaidong@nuaa.edu.cn
			Dong Zhao	Anhui University	zhaodong@ahu.edu.cn
4	Integrating Intelligence into Space: Innovation in the Fusion of Spaceplane Actuation and Artificial Intelligence	JdbV9Y	Jiaojiao Xu	Qing'an Group Co., Ltd.	Xujj014@avic.com
			Feng Zhao	Qing'an Group Co., Ltd.	Zhaof027@avic.com
5	Satellite Swarms: Dynamics, Planning,	m2Jq5H	Fan Zhang	Sun Yat-sen University	zhangfan6@mail.sysu.edu.cn

	and Control		Dong Ye	Harbin Institute of Technology	yed@hit.edu.cn
			Jihe Wang	Sun Yat-sen University	wangjihe@mail.sysu.edu.cn
			Caizhi Fan	National University of Defense Technology	caizhifan@nudt.edu.cn
6	Intelligent Navigation and Positioning Technologies for Unmanned Systems in Complex Environments	0g7myR	Pin Lyu	Nanjing University of Aeronautics and Astronautics	lvpin@nuaa.edu.cn
			Qian Meng	Southeast University	qianmeng@seu.edu.cn
			Qieqie Zhang	Nanjing University of Aeronautics and Astronautics	zhangqieqie@nuaa.edu.cn
			Jun Xiong	Nanjing University of Posts and Telecommunications	xiongjun@njupt.edu.cn
			Cheng Yuan	Nanjing University of Aeronautics and Astronautics	ycauto@nuaa.edu.cn
7	Deep learning assisted autonomous navigation in GNSS-denied	c4gnuM	Jinwen Wang	Nanjing University of Science and Technology	javedwjw@163.com
			Hui Zhao	Beijing Information Science and Technology University	zhhui@bistu.edu.cn
8	Autonomous Intelligence and Game-Theoretic Confrontation for Cross-Domain Vehicles	PuGkk8	Wei Huang	National University of Defense Technology	gladrain2001@163.com
			Pei Dai	Xidian University	daipei@xidian.edu.cn
			Shuangxi Liu	National University of Defense Technology	lsxdouble@163.com

9	Control Technology of Aerospace Multi-Agent Formations	44u1Ix	Hongshi Lu	Northwestern Polytechnical University	luhs@nwpu.edu.cn
			Aijun Li	Northwestern Polytechnical University	liaijun@nwpu.edu.cn
			Changqing Wang	Northwestern Polytechnical University	wangcq@nwpu.edu.cn
10	Intelligent Guidance and Safety Control of Morphing/VTOL UAV Swarms	tGs4fq	Ban Wang	Northwestern Polytechnical University	wangban@nwpu.edu.cn
			Lingxia Mu	Xi' an University of Technology	mulingxia@xaut.edu.cn
			Xianghong Xue	Xi' an University of Technology	xhxue@xaut.edu.cn
			Yujiang Zhong	Northwestern Polytechnical University	zhongyujiang@nwpu.edu.cn
11	Embodied Intelligence Technology for Aviation-Oriented Application Scenarios	11ZIWb	Weijia Wang	Flight Automatic Control Research Institute, AVIC	weijia_hust@163.com
12	Autonomous intelligent flight control	cqFx0E	Yanguo Hu	Shenyang Aircraft Design and Research Institute	hygdut2011@126.com
			Kai Liu	DaLian University of Technology	carsonliu@dlut.edu.cn